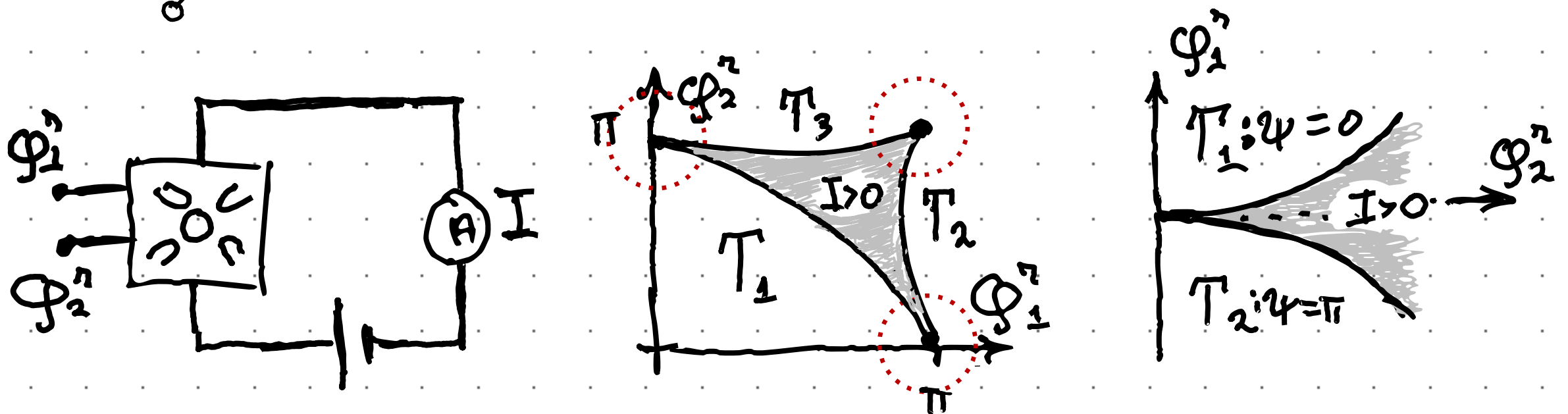


SOFT CONSTRAINED TOPOLOGICAL TRANSITION

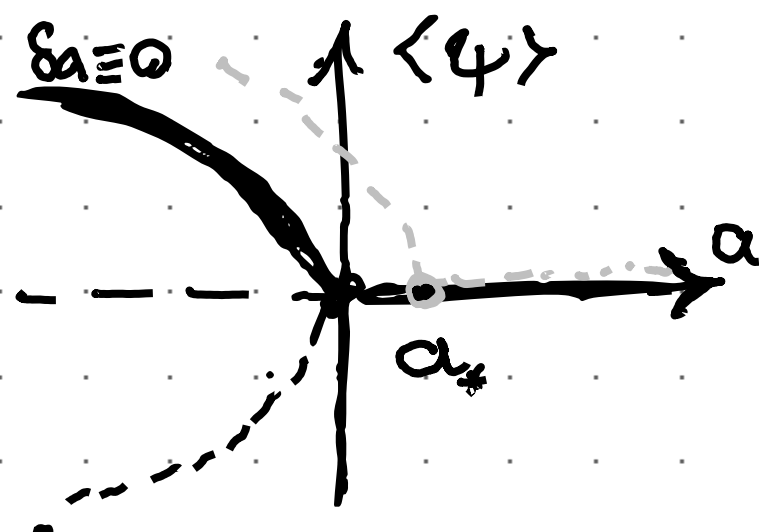
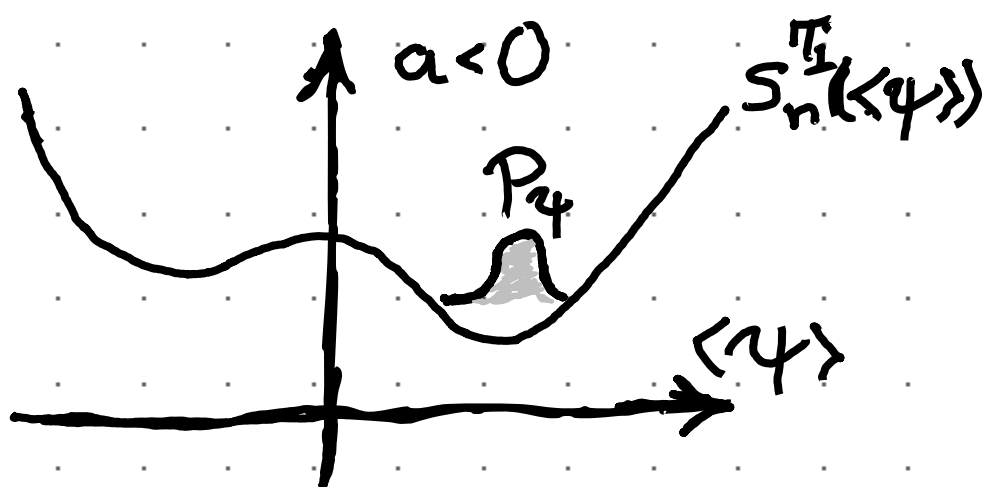
JĀNIS ERDMANIS, ĀRPĀD LUKĀCS, YULI V. NAZAROV

$$\mathcal{Z} = \int \left\{ \text{Circuit Diagram} \right\} D\vec{\varphi}(\tau)$$

$$S_n = \text{Circuit Diagram} = \frac{1}{2} \sum_{\mathbf{A}} \sum_{\mathbf{B}} \text{Tr} \left\{ \log \left[1 + \frac{\Gamma_{\mathbf{P}}}{4} (G_{\mathbf{A}} G_{\mathbf{B}} + G_{\mathbf{B}} G_{\mathbf{A}} - 2) \right] \right\}$$



$$\Rightarrow S_n^{\Gamma_1} \approx \text{Tr} \left[-2\varepsilon\psi + \frac{1}{2}(a + \delta a)\psi^2 + \frac{1}{4}b\psi^4 \right]$$



$$\langle S_n(a + \delta a, \psi) \rangle \stackrel{?}{=} S_n(a, \langle \psi \rangle) + \langle S_n^{(2)} \rangle(a, \langle \psi \rangle) \stackrel{?}{=} S_n(a_*, \langle \psi \rangle)$$

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